Mapping Report 2024-25

Since the 2024 AGM Report, these are the areas that have been worked on:

Areas in GREEN are new maps

Areas in RED would greatly benefit from additional surveying.

Robin Hoods Bay	Updates by Chris Wright for Autumn Series
Saltburn	Updates by Chris Wright for Autumn Series
Albert Park	Updates by Chris Wright for Autumn Series
Birk Brow	Partially updated by Patrick Smyth
Hardwick Country Park	New map by Ann Cranke
Wilton/Lazenby Woods	Updated by Paul Taylor
Eston Moor	Revised by Charles Mayes (escarpment) and Paul Taylor (plateau)
Coatham Links Golf	Updates by Alan and Ann Cranke
Romanby Golf	Updates by Rob Bailey
Silton Forest	Partial revisions by Ann Cranke and Paul Taylor
Shildon	New map by Martyn Dean
Newton Aycliffe	New map by Martyn Dean
Preston Park	Updated by Nick Martin
Yarm	Updated by Martyn Dean
Darlington	Updated and extended by Phill Batts
South Gare	Updated by Ann Cranke
Standing Stones Rigg	Extended and updated by Paul Taylor
Dale Town Common	Extended by Rob Bailey to include Little Moor (new area) for the November events.
Catterick Village	New map by Martyn Dean

/ continued

Present and Future Projects

Guisborough	Presently being remapped by Martyn Dean
Northallerton	Presently being remapped by Martyn Dean. Including the north of the town with the new housing and industrial estates
Jugger Howe Moor	The tragic wild fire of 2025 has resulted in a temporary loss of our use of much of Fylingdales Moor. However, some areas have not been affected including Jugger Howe Moor. We have negotiated the use of Jugger Howe for the 2027 JHI and October Odyssey. The terrain is heather moorland plateau which has been well managed, with steeper, well contoured valley sides. It is a bit exposed but, being an ex-military training area, it has hard standing for car parking.

The following areas are said to need a bit of an update:-

Birk Brow, Errington, Ropner Park, Darlington South Park, Boltby and **Silton.**

Any offers?

Potential new areas

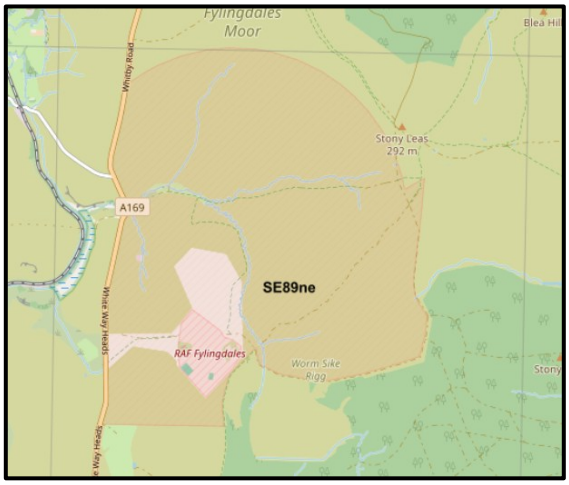
Ugglebarnby Moor, Sneaton (suggested by John Green)

A small area, but capable of providing a limited classic orienteering event, situated at Red Gate on the B1416 between the potash mine and Littlebeck. The terrain is unmanaged moorland with rapidly colonising pine and birch woodland. There is a small coverage of mature and runnable pine plantation, some old quarry workings and a path network at the northern (Ugglebarnby – Pokeham Brow) end. The ownership is Grosmont Estate, an organisation we haven't contacted yet.

Other mapping reports:

LiDAR coverage

ntil recently we have not been able to download EA LiDAR data for a large area of land surrounding RAF Fylingdales. This has affected Fylingdales Moor and Sneaton Forest. This area is now available, so the Fylingdales Moor and Sneaton Forest maps will be amended with LiDAR contours. Fylingdales did originally have the benefit of a photogrammetric plot, purchased from Stirling Surveys, but Sneaton has only been surveyed by traditional methods. The updated contours will take time to produce, but a start has already been made.



This is not just good news for CLOK, because LiDAR is now available for EBOR's Cloughton Woods, Raincliffe Woods, Harwood Dale Forest, Dalby Forest, Newtondale, Wykeham and Cropton Forest.

The immediate vicinity of the RAF base is still unavailable according to the EA map.

CLOK map layout

A reminder. The agreed layout needs to be applied to all CLOK maps.

The specific details of the new map layout are on the CLOK web site in the 'Event Organisation Toolkit' – Planning section.

However, ‘off the peg’ layout files can be found on the CLOK Google Drive.

Please note that on any reproduction of a CLOK map such as RouteGadget, there is credit information that must be included. The most important item is the Ordnance Survey Licence details including the licence number. This is a legal requirement.

CLOK Google Drive

The Mapping spreadsheet on Google Drive is regularly updated so that anybody planning an event should be aware of the status of any mapped area. PLEASE CHECK.

Current OCAD map files are stored on the Google Drive. Please be very careful when accessing these files to make sure that only the most up to date map is used. The latest map should now have a date as part of the file name in the form ‘Clokland Wood 211019’; i.e. year, month, day so that they automatically fall to the bottom of the list in the folder.

The issue is that in some cases older or partial maps have been used and even partially updated. **The rule is that corrections are only applied to the full canvas. Any partial maps should be deleted after the event or moved to ‘Archive Map Files’.**

If in doubt, please contact me or Phill Batts.

Full Canvas versus Partial Maps

This is a question that may have to be resolved by more than just myself.

I’ll use the area around Cod Beck as an example. At the moment, we have an OCAD file covering Arncliffe, Scarth Wood Moor, Clain Wood, Bracken Banks and Cod Beck. In the past we have had events that have used several of these areas for one event. The last event used Cod Beck and Scarth Wood Moor and the next event will probably use the same areas. We haven’t included Arncliffe or Clain Wood, probably for the reasons that:

a. some of it is way out of date (Arncliffe) or a bit out of date (Clain)
b. some is very physical
c. the status of events hasn’t required the extra length and technicality
d. there are too many landowners to negotiate/pay.

The advantage of having all these adjacent areas on one canvas is that the OCAD file has the same symbol and colour sets and the whole file can be managed as one unit for georeferencing and rotation. Where the difficulty arises is the case when a chunk of the map is cropped to make a partial map. If that file is uploaded to the Google Drive, it may be picked up by a mapper or planner who may start to edit it on its own without adding edits to the main canvas. If this happens, the full canvas and the partial map become useless.

On the other hand we can restrict the map file to just one unit at a time. Say, for example, Cod Beck Woods. If the planner needs to cross the fence onto the moor we would need to import the Scarth Wood Moor into the Cod Beck map. This would need to have the same scale, georeferencing and rotation. And if the two partial maps use non-identical symbol and colour sets, we end up with twice the number of symbols and colours. If we then import another map unit, the problem is compounded.

Theoretically this should work for one event but again, if this Event Race Map finds its way on to the Google Drive it becomes a nightmare.

Whatever the system, Event Race Maps must be archived (Archive Events) and never be uploaded to Current Map Files in Google Drive.

Paul Taylor
October 2026